



AUTOMATIC OIL SPILL RECOGNITION AND GEOPOSITIONING
INTEGRATED IN A MARINE MONITORING NETWORK



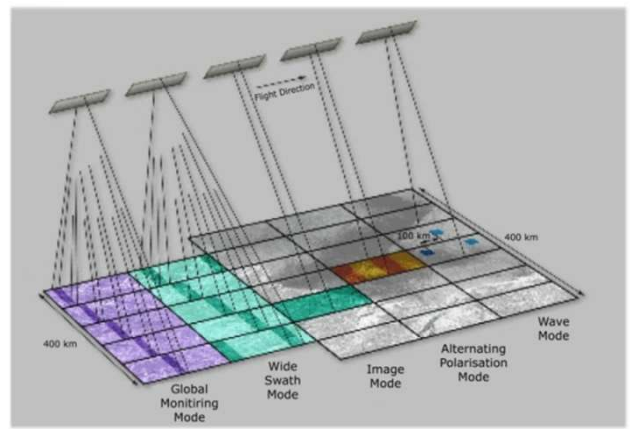
A EU 7TH FRAMEWORK PROGRAMME
PROJECT

**THE ARGOMARINE PROJECT:
A LOW COST PLATFORM TO INTEGRATE DATA AND
THE EXPLORATORY USE OF NEW TOOLS IN
MONITORING OIL SPILL**

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Maritime Information System

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AUV
Autonom
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vehicle

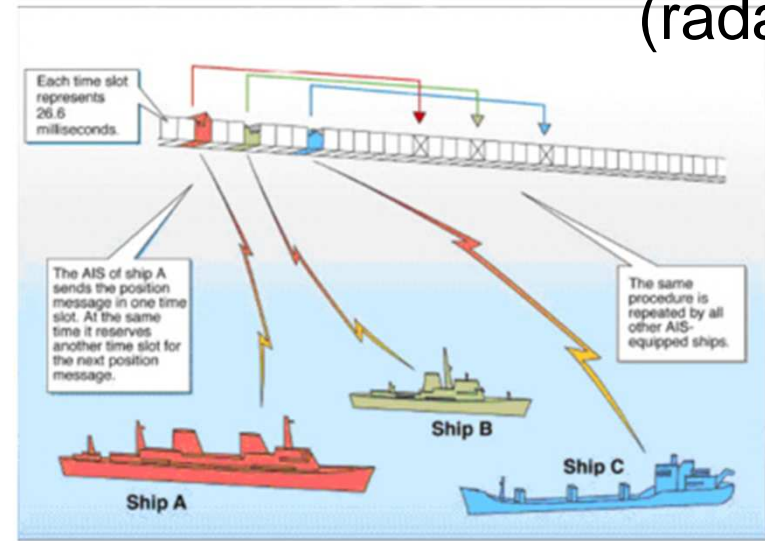
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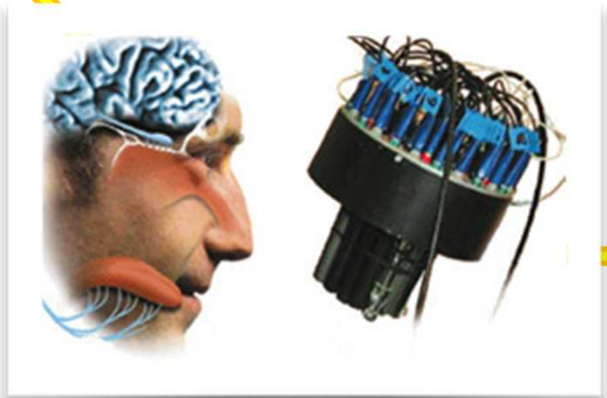
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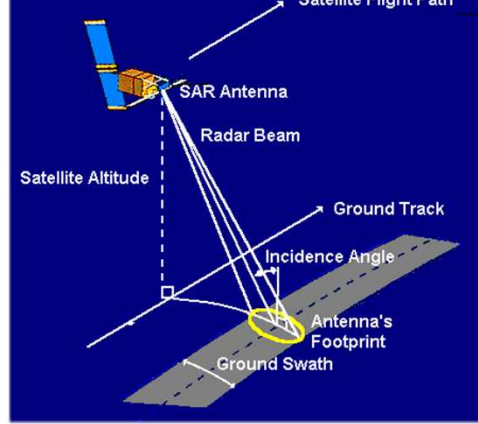
AIS and V
(radar)



Electronic Noses

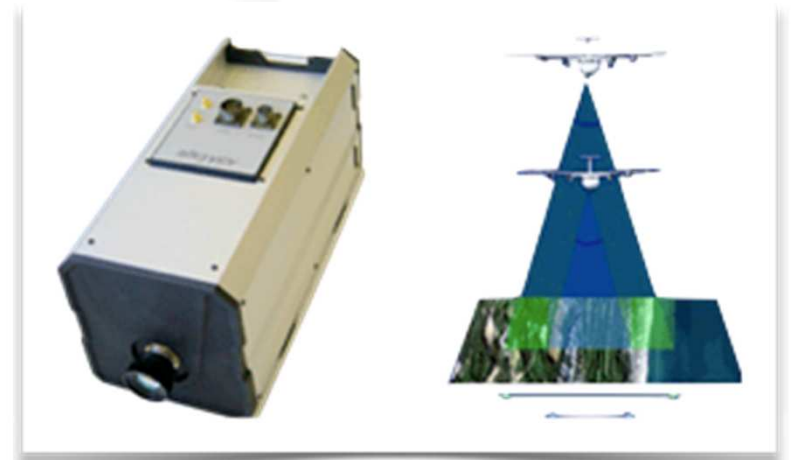


SAR sensors (Synthetic Aperture Radar from ERS-1, ERS-2, ENVISAT-R, TerraSAR-X and Cosmo-SkyMed

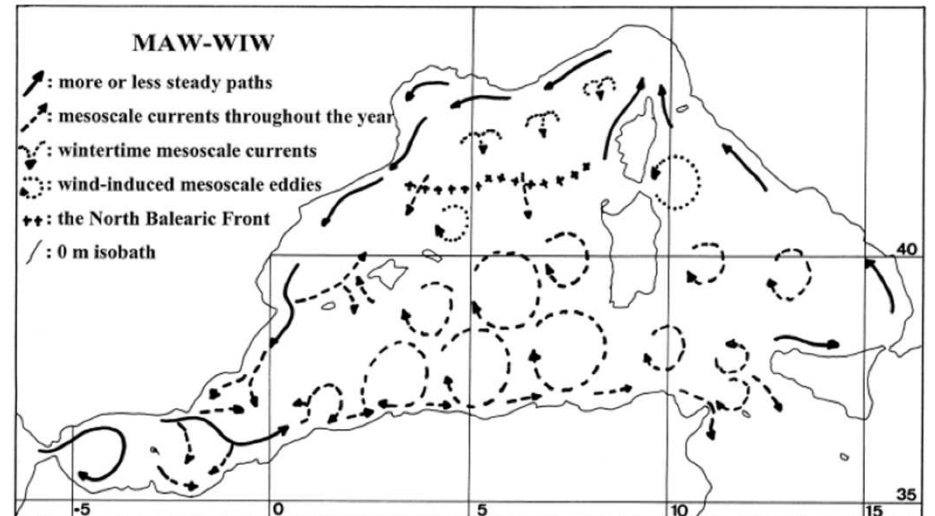


Amorphous spill	
Old zigzag spill	
Fresh zigzag spill	
Old straight spill	
Fresh straight spill	

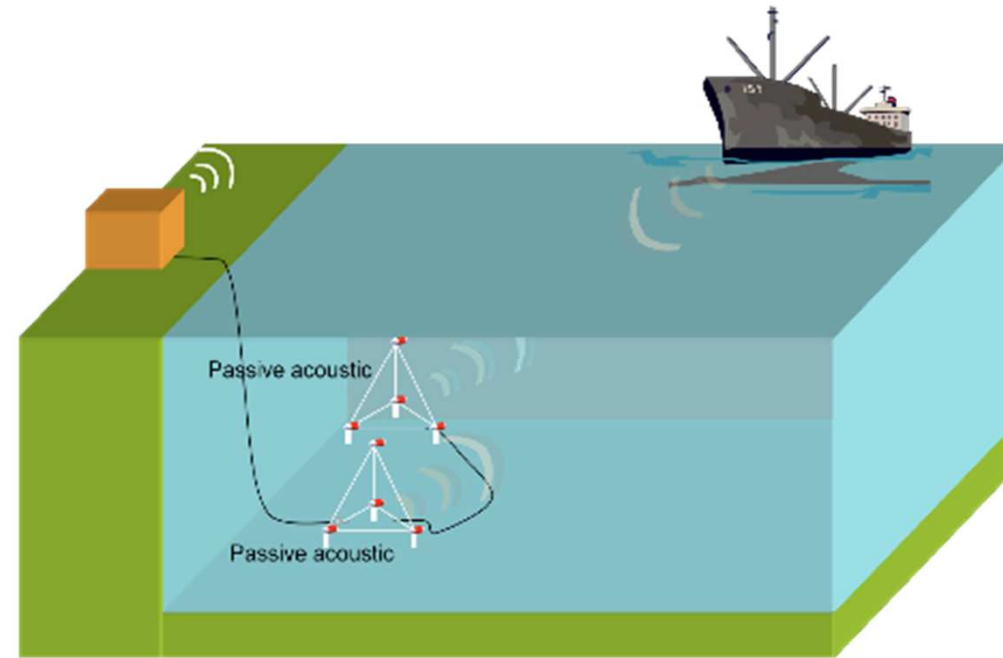
Hyperspectral sensors on vessels and airbornes



3) Mathematical simulation models



Passive acoustic sensors



Electronic noses on buoys for Autonomous Underwater Vehicles (AUV)

